1. Stop motors before disarming. (YES)
2. Camera B second if statement needs correction (2nd “else if” is missing). (YES)
3. Increase dArea value (grabbing just short of object). (YES)
4. Adjust pwm value for claw (opening too much). (YES)
5. Make UUV to move forward 10 feet. (YES)
6. Delay start time to 10 minutes.

CAUTION

Will move forward once pixhawk is armed for 24 seconds

Will move backwards once object is grabbed for 6 seconds